



Common Fixed Point Theorems for Mappings Satisfying ϕ Implicit Relation in G -Metric Spaces

Rashwan A. Rashwan^{1*} and Samira M. Saleh²

¹Department of Mathematics, Faculty of Science, Assiut University, Assiut71516, Egypt

²Department of Mathematics, Faculty of Science, Assiut University, Assiut, Egypt

Abstract: In this paper some common fixed point theorems are established for two and four mappings satisfying ϕ -implicit relation in G -metric spaces. Also, a common fixed point theorem for T -contraction mapping is proved. our results are improve the results of Popa and Patriciu [24]. An example is given to justify some of our results.

Keywords: G -metric space, common fixed point, weak-compatible maps, ϕ -implicit relation, T -contraction

1. INTRODUCTION

Jungck [5] proved a common fixed point theorem for commuting mappings as generalizing the Banach's fixed point theorem. The concept of the commutativity has generalized in several ways. For this Sessa [25] introduced the concept of weakly commuting mappings, Jungck [6] extend this concept to compatible maps. In 1998, Jungck and Rhoades [7] introduced the notion of weak compatibility and showed that compatible maps are weakly compatible but the converse need not to be true, for example see Pathak [21].

The notion of G -metric space was introduced by Mustafa and Sims [17, [18] as a generalization of the notion of metric spaces. Afterwards Mustafa, Sims and others authors introduced and developed several fixed point theorems for mappings satisfying different contractive conditions in G -metric spaces, also extend known theorems in metric spaces to G -metric spaces see [4, 9-20, 26] and many other papers.

Beiranvand, Moradi, Omid and Pazandeh [3] introduce the classes of T -contraction and T -contractive mappings, which are depending on another function. Moradi in [10] introduce the T -Kannan contractivemapping. Morales and Rojas [11, 12] have extended the concept of T -contraction mappings to cone metric space by

proving fixed point theorems for T -Kannan, T -Chatterjea T -Zamfirescu, T -weakly contraction mappings. Sumitra, Rhymend Uthariaraj and Hemavathy [27] proved a fixed point theorem in the setting of cone metric space for T -Hardy-Rogers type contraction condition.

Karayian and Telici [8] and Shatanawi [26] proved some fixed point theorems for mappings satisfying ϕ - maps. Popa [22, 23] initiated the study of fixed points for mappings satisfying implicit relations. Altun and Turkoglu [2] introduced a new type of implicit relations satisfying ϕ -map. Popa and Patriciu [24] proved a fixed point theorem in a complete G -metric spaces for mappings satisfying ϕ -implicit relation.

The purpose of this paper is to study some common fixed point theorems for two and four mappings satisfying ϕ -implicit relation in G -metric spaces. Also, a common fixed point theorem for T -contraction mapping is proved. our results are improve the results of Popa and Patriciu [24].

2. PRELIMINARIES

Definition 2.1. [18] Let X be a nonempty set, and let $G : X^3 \rightarrow [0, \infty)$, be a function satisfying:

$$(G_1) G(x, y, z) = 0 \text{ if } x = y = z,$$

(G₂) $0 < G(x, x, y)$, for all $x, y \in X$, with $x \neq y$,

(G₃) $G(x, x, y) \leq G(x, y, z)$, $\forall x, y, z \in X$, with $z \neq y$,

(G₄) $G(x, y, z) = G(x, z, y) = G(y, z, x) \dots$, (symmetry in all three variables),

(G₅) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$, $\forall x, y, z, a \in X$, (rectangle inequality).

Then the function G is called a generalized metric, or more specifically a G -metric on X , and the pair (X, G) is called a G -metric space.

Definition 2.2. [18] Let (X, G) be a G -metric space, a sequence (x_n) is said to be

- (i) G -convergent if for every $\varepsilon > 0$, there exists an $x \in X$, and $k \in \mathbf{N}$ such that for all $m, n \geq k$, $G(x, x_n, x_m) < \varepsilon$.
- (ii) G -Cauchy if for every $\varepsilon > 0$, there exists an $k \in \mathbf{N}$ such that for all $m, n, p \geq k$, $G(x_m, x_n, x_p) < \varepsilon$, that is $G(x_m, x_n, x_p) \rightarrow 0$ as $m, n, p \rightarrow \infty$.
- (iii) A space (X, G) is said to be G -complete if every G -Cauchy sequence in (X, G) is G -convergent.

Definition 2.3. [18] A G metric space X is symmetric if $G(x, y, y) = G(y, x, x)$ for all $x, y \in X$.

Lemma 2.1. [18] Let (X, G) be a G -metric space. Then the following are equivalent:

- (i) (x_n) is convergent to x ,
- (ii) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$,
- (iii) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow \infty$,
- (iv) $G(x_n, x_m, x) \rightarrow 0$ as $n, m \rightarrow \infty$,

Lemma 2.2. [18] Let (X, G) be a G -metric space. Then the following are equivalent:

- (i) The sequence (x_n) is G -Cauchy,
- (ii) for every $\varepsilon > 0$, there exists $k \in \mathbf{N}$ such that $G(x_n, x_m, x_m) < \varepsilon$ for $m, n \geq k$.

Lemma 2.3. Mustafa and Sims [18] Let (X, G) be a G -metric space. Then the function $G(x, y, z)$ is jointly continuous in all three of its variables.

Definition 2.4. Let T and S be self maps of a

nonempty set X . If $w = Tx = Sx$ for some $x \in X$, then x is called a coincidence point of T and S and w is called a point of coincidence of T and S .

Definition 2.5. Two self -mappings T and S are said to be weakly compatible if they commute at their coincidence points, that is, $Tx = Sx$ implies that $TSx = STx$.

3. IMPLICIT RELATIONS

Definition 3.1. Popa and Patriciu [24] A function $f: [0, \infty) \rightarrow [0, \infty)$ is called a ϕ -function, $f \in \phi$, if f is a nondecreasing function such that $\sum_{n=1}^{\infty} f^n(t) < \infty$, for all $f(t) < t$ for $t > 0$ and $f(0) = 0$.

Definition 3.2. Let F_ϕ be the set of all continuous functions $F(t_1, \dots, t_6): \mathbf{R}_+^6 \rightarrow \mathbf{R}$ such that:

(F₁): F is nonincreasing in t_5 ,

(F₂): there exists a function $\phi_1, \phi_2 \in \phi$ such that for all $u, v \geq 0$, with

(F_a): $F(u, v, v, u, u + v, 0) \leq 0$ implies $u \leq \phi_1(v)$,

(F_b): $F(u, v, u, v, 0, u + v) \leq 0$ implies $u \leq \phi_2(v)$,

(F₃): there exists a function $\phi_3 \in \phi$ such that for all $t, t' > 0$, $F(t, t, 0, 0, t, t') \leq 0$ implies $t \leq \phi_3(t')$.

Example 3.3. $F(t_1, \dots, t_6) = t_1 - at_2 - bt_3 - ct_4 - dt_5 - et_6$, where $a > 0, b, c, d, e \geq 0, a + b + c + 2d + e < 1$.

(F₁): Obviously. $F(t_1, \dots, t_6)$

(F₂): Let $u, v \geq 0$, and $F(u, v, v, u, u + v, 0) = u - av - bv - cu - d(u + v) \leq 0$ which implies $u \leq \frac{a+b+d}{1-c-d}v$. F_a is satisfied for $\phi_1(t) = \frac{a+b+d}{1-c-d}t$. Similarly $F(u, v, u, v, 0, u + v) = u - av - bu - cv - e(u + v) \leq 0$ which implies $u \leq \frac{a+c+e}{1-b-e}v$. F_b is satisfied for $\phi_2(t) = \frac{a+c+e}{1-b-e}t$.

(F₃): Let $t, t' > 0$ be and $F(t, t, 0, 0, t, t') = t - at - bt - et' \leq 0$ which implies

$t \leq \frac{e}{1-(a+d)}t'$ and F_3 is satisfied for $\phi_3(t) = \frac{e}{1-(a+d)}t$.

Example 3.4 $F(t_1, \dots, t_6) = t_1 - k \max\{t_2, t_3, t_4, t_5, t_6\}$, where $k \in (0, \frac{1}{2})$.

(F₁): Obviously.

(F₂): Let $u, v \geq 0$, and $F(u, v, v, u, u + v, 0) = F(u, v, u, v, 0, u + v) = u - k \max\{u, v, u + v\} \leq 0$. Hence $u \leq \frac{k}{1-k} v$ and F_a is satisfied for $\phi_1(t) = \frac{k}{1-k} t$. Similarly $F(u, v, u, v, 0, u + v) = u - k \max\{u, v, u + v\} \leq 0$. Then $u \leq \frac{k}{1-k} v$ and F_b is satisfied for $\phi_2(t) = \frac{k}{1-k} t$.

(F₃): Let $t, t' > 0$ be and $F(t, t, 0, 0, t, t') = t - k \max\{t, t'\} \leq 0$ if $t > t'$, then $t(1 - k) \leq 0$, a contradiction. Hence $t \leq t'$ which implies $t \leq kt'$ and F_3 is satisfied for $\phi_3(t) = kt$.

Example 3.5 $F(t_1, \dots, t_6) = t_1 - k \max\{t_2, t_3, t_4, \frac{t_5+t_6}{2}\}$, where $k \in (0, 1)$.

(F₁): Obviously.

(F₂): Let $u, v \geq 0$, and $F(u, v, v, u, u + v, 0) = F(u, v, u, v, 0, u + v) = u - k \max\{u, v, \frac{u+v}{2}\} \leq 0$. If $u > v$, then $u(1 - k) \leq 0$, a contradiction. Hence $u \leq v$ which implies $u \leq kv$ and F_a is satisfied for $\phi_1(t) = kt$. Similarly $F(u, v, u, v, 0, u + v) = u - k \max\{u, v, \frac{u+v}{2}\} \leq 0$. Then $u \leq kv$ and F_b is satisfied for $\phi_2(t) = kt$.

(F₃): Let $t, t' > 0$ be and $F(t, t, 0, 0, t, t') = t - k \max\{t, t'\} \leq 0$ if $t > t'$, then $t(1 - k) \leq 0$, a contradiction. Hence $t \leq t'$ which implies $t \leq kt'$ and F_3 is satisfied for $\phi_3(t) = kt$.

For more examples see [24], where those examples also satisfying (F_b).

4. MAIN RESULTS

Lemma 4.1. Let (X, G) be a G -metric space and $T, f: (X, G) \rightarrow (X, G)$ two mappings such that T is one to one and

$$F(G(Tfx, Tfy, Tfy), G(Tx, Ty, Ty), G(Tx, Tfx, Tfx), G(Ty, Tfy, Tfy), G(Tx, Tfy, Tfy), G(Ty, Tfx, Tfx)) \leq 0, \quad (1)$$

for all $x, y \in X$ and F satisfying property (F₃) Then, f has at most a fixed point.

Proof. Suppose that $u = f u$ and $v = f v$. Then by (1) we have successively

$$F(G(Tfu, Tfv, Tfv), G(Tu, Tv, Tv),$$

$$G(Tu, Tfu, Tfu), G(Tv, Tfv, Tfv), G(Tu, Tfv, Tfv), G(Tv, Tfu, Tfu)) \leq 0,$$

by (F₃) we obtain that

$$G(Tu, Tv, Tv) \leq \phi_3(G(Tv, Tu, Tu)).$$

Similarly, we obtain that

$$G(Tv, Tu, Tu) \leq \phi_3(G(Tu, Tv, Tv)).$$

Hence

$$G(Tu, Tv, Tv) \leq \phi_3(G(Tv, Tu, Tu)) \leq \phi_3^2(G(Tu, Tv, Tv)) < G(Tu, Tv, Tv),$$

which is a contradiction. Hence $Tu = Tv$, since T is one to one then $u = v$.

Theorem 4.1. Let (X, G) be a G -metric space. Assume that T and f are two self mappings of (X, G) . Assume that $T(X)$ is a G -complete subspace of X and T is one to one mapping. If T and f satisfying inequality (1) for all $x, y \in X$, where $F \in F_\phi$, then f has a unique fixed point in X . Moreover, if T and f are commuting at the fixed points of f , then T and f have a unique common fixed point.

Proof. Let x_0 be an arbitrary point of X . Define a sequence (x_n) in X such that $x_{n+1} = f x_n$ for each $n = 0, 1, \dots$. Then by (1) we have successively

$$F(G(Tfx_{n-1}, Tfx_n, Tfx_n), G(Tx_{n-1}, Tx_n, Tx_n), G(Tx_{n-1}, Tfx_{n-1}, Tfx_{n-1}), G(Tx_n, Tfx_n, Tfx_n), G(Tx_{n-1}, Tfx_n, Tfx_n), G(Tx_n, Tfx_{n-1}, Tfx_{n-1})) \leq 0,$$

$$F(G(Tx_n, Tx_{n+1}, Tx_{n+1}), G(Tx_{n-1}, Tx_n, Tx_n), G(Tx_{n-1}, Tx_n, Tx_n), G(Tx_n, Tx_{n+1}, Tx_{n+1}), G(Tx_{n-1}, Tx_{n+1}, Tx_{n+1}), G(Tx_n, Tx_n, Tx_n)) \leq 0.$$

By (F₁) and (G₅) we obtain

$$F(G(Tx_n, Tx_{n+1}, Tx_{n+1}), G(Tx_{n-1}, Tx_n, Tx_n), G(Tx_{n-1}, Tx_n, Tx_n), G(Tx_n, Tx_{n+1}, Tx_{n+1}), G(Tx_{n-1}, Tx_n, Tx_n) + G(Tx_n, Tx_{n+1}, Tx_{n+1}), 0) \leq 0.$$

By (F_a) we obtained

$$\begin{aligned}
& G(Tx_n, Tx_{n+1}, Tx_{n+1}) \\
& \leq \phi_1(G(Tx_{n-1}, Tx_n, Tx_n)) \\
& \leq \phi_1^2(G(Tx_{n-2}, Tx_{n-1}, Tx_{n-1})) \\
& \quad \vdots \\
& \leq \phi_1^n(G(Tx_0, Tx_1, Tx_1)).
\end{aligned}$$

Therefore

$$\begin{aligned}
& G(Tx_n, Tx_m, Tx_m) \\
& \leq G(Tx_n, Tx_{n+1}, Tx_{n+1}) + \dots \\
& + G(Tx_{m-1}, Tx_m, Tx_m) \\
& \leq \phi_1^n(G(Tx_0, Tx_1, Tx_1)) + \dots \\
& + \phi_1^{m-1}(G(Tx_0, Tx_1, Tx_1)) \\
& = \sum_{k=n}^{m-1} \phi_1^k(G(Tx_0, Tx_1, Tx_1)).
\end{aligned}$$

Since, $\sum_{k=n}^{\infty} \phi_1^k(G(Tx_0, Tx_1, Tx_1)) < \infty$ then for any $\varepsilon > 0$, there exists $k \in \mathbb{N}$ such that for $m > n \geq$

$k, \sum_{k=n}^{m-1} \phi_1^k(G(Tx_0, Tx_1, Tx_1)) < \varepsilon$. Hence by Lemma (2.2) (Tx_n) is a G -Cauchy sequence. Since $T(X)$ is a G -complete metric subspace of X , there exists a point q in $T(X)$ such that $\lim_{n \rightarrow \infty} Tx_n = q$. Also, we can find a point $u \in X$ such that $Tu = q$. Now, we prove $Tu = Tfu$. By (1) we have

$$\begin{aligned}
& F(G(Tfx_n, Tfu, Tfu), G(Tx_n, Tu, Tu), \\
& G(Tx_n, Tfx_n, Tfx_n), G(Tu, Tfu, Tfu), \\
& G(Tx_n, Tfu, Tfu), G(Tu, Tfx_n, Tfx_n)) \leq 0, \\
& F(G(Tx_{n+1}, Tfu, Tfu), G(Tx_n, Tu, Tu), G(Tx_n, \\
& Tx_{n+1}, Tx_{n+1}), G(Tu, Tfu, Tfu), \\
& G(Tx_n, Tfu, Tfu), G(Tu, Tx_{n+1}, Tx_{n+1})) \leq 0.
\end{aligned}$$

Letting n tend to infinity, we obtain

$$\begin{aligned}
& F(G(Tu, Tfu, Tfu), 0, 0, G(Tu, Tfu, Tfu), \\
& G(Tu, Tfu, Tfu), 0) \leq 0
\end{aligned}$$

By (F_a) we have $G(Tu, Tfu, Tfu) \leq \phi_1(0) = 0$, hence $G(Tu, Tfu, Tfu) = 0$, then $Tu = Tfu$. Since T is one to one, $fu = u$. By Lemma (4.1), u is the unique fixed point of f . Moreover, if T and f are commuting at the fixed points of f , then $fTu = Tfu = u$ this implies that Tu is another fixed point of f . By uniqueness of

fixed point of f , we have $Tu = u$. Hence $Tu = fu = u$ is a unique common fixed point of f and T . If we put $T = I$, where I is the identity mapping, we have the following Corollary.

Corollary 4.1. (Theorem 4.2 [24]) Let (X, G) be a complete G -metric space. Assume that T satisfying the condition

$$\begin{aligned}
& F(G(Tx, Ty, Ty), G(x, y, y), G(x, Tx, Tx), \\
& G(y, Ty, Ty), G(x, Ty, Ty), G(y, Tx, Tx)) \leq 0,
\end{aligned}$$

for all $x, y \in X$, where $F \in \mathbf{F}_\phi$, then T has a unique fixed point.

The following Lemmas are fundamental in the sequel.

Lemma 4.2. Abbas and Rhoades [1] Let T and S be weakly compatible self-mappings of nonempty set X . If T and S have a unique point of coincidence $w = Tx = Sx$, then w is the unique common fixed point of T and S .

Lemma 4.3. Let (X, G) be a G -metric space and $T, S : (X, G) \rightarrow (X, G)$ two mappings such that

$$\begin{aligned}
& F(G(Tx, Ty, Ty), G(Sx, Sy, Sy), \\
& G(Sx, Tx, Tx), G(Sy, Ty, Ty), \\
& G(Sx, Ty, Ty), G(Sy, Tx, Tx)) \leq 0, \quad (2)
\end{aligned}$$

for all $x, y \in X$ and F satisfying property (F_3) . Then, T and S have at most a point of coincidence.

Proof. Suppose that $u = Tp = Sp$ and $v = Tq = Sq$. Then by (2) we have successively

$$\begin{aligned}
& F(G(Tp, Tq, Tq), G(Sp, Sq, Sq), G(Sp, Tp, Tp), \\
& G(Sq, Tq, Tq), G(Sp, Tq, Tq), \\
& G(Sq, Tp, Tp)) \leq 0 \\
& F(G(u, v, v), G(u, v, v), 0, 0, G(u, v, v), \\
& G(v, u, u)) \leq 0,
\end{aligned}$$

by (F_3) we obtain that

$$G(u, v, v) \leq \phi_3(G(v, u, u)).$$

Similarly, we obtain that

$$G(v, u, u) \leq \phi_3(G(u, v, v)).$$

Hence

$$\begin{aligned}
& G(u, v, v) \leq \phi_3(G(v, u, u)) \\
& \leq \phi_3^2(G(u, v, v)) \\
& < G(u, v, v),
\end{aligned}$$

which is a contradiction. Hence $u = v$.

Lemma 4.4. Let (X, G) be a G -metric space and $A, B, S, T : (X, G) \rightarrow (X, G)$ such that

$$F(G(Tx, By, By), G(Sx, Ay, Ay), G(Sx, Tx, Tx), G(Ay, By, By), G(Sx, By, By), G(Ay, Tx, Tx)) \leq 0, \tag{3}$$

for all $x, y \in X$ and F satisfying property (F_3) . Then, A, B, S and T have at most a common fixed point.

Proof. Suppose that $p = Tp = Sp = Ap = Bp$ and $q = Tq = Sq = Aq = Bq, p \neq q$. Then by (3) we have successively

$$F(G(Tp, Bq, Bq), G(Sp, Aq, Aq), G(Sp, Tp, Tp), G(Aq, Bq, Bq), G(Sp, Bq, Bq), G(Aq, Tp, Tp)) \leq 0,$$

$$F(G(p, q, q), G(p, q, q), 0, 0, G(p, q, q), G(q, p, p)) \leq 0,$$

by (F_3) we obtain that

$$G(p, q, q) \leq \phi_3(G(q, p, p)).$$

Similarly, we obtain that

$$G(q, p, p) \leq \phi_3(G(p, q, q)).$$

Hence

$$G(p, q, q) \leq \phi_3(G(q, p, p)) \leq \phi_3^2(G(p, q, q)) < G(p, q, q),$$

which is a contradiction. Hence $p = q$.

Theorem 4.2. Let (X, G) be a G -metric space and $T, S : (X, G) \rightarrow (X, G)$ satisfying inequality (2) for all $x, y \in X$, where $F \in F_\phi$. If $T(X) \subseteq S(X)$ and $S(X)$ is a G -complete metric subspace of (X, G) , then T and S have a unique point of coincidence. Moreover, if T and S are weakly compatible, then T and S have a unique common fixed point.

Proof. Let x_0 be an arbitrary point of X since $T(X) \subseteq S(X)$ we can choose $x_1 \in X$ such that $Tx_0 = Sx_1$. Continuing this process, having chosen x_n in X , we obtain x_{n+1} such that $Tx_n = Sx_{n+1}$. Then, by (2) we have successively

$$F(G(Tx_{n-1}, Tx_n, Tx_n), G(Sx_{n-1}, Sx_n, Sx_n),$$

$$G(Sx_{n-1}, Tx_{n-1}, Tx_{n-1}), G(Sx_n, Tx_n, Tx_n), G(Sx_{n-1}, Tx_n, Tx_n), G(Sx_n, Tx_{n-1}, Tx_{n-1})) \leq 0,$$

$$F(G(Sx_n, Sx_{n+1}, Sx_{n+1}), G(Sx_{n-1}, Sx_n, Sx_n), G(Sx_{n-1}, Sx_n, Sx_n), G(Sx_n, Sx_{n+1}, Sx_{n+1}), G(Sx_{n-1}, Sx_{n+1}, Sx_{n+1}), 0) \leq 0.$$

By (F_1) and (G_5) we obtain

$$F(G(Sx_n, Sx_{n+1}, Sx_{n+1}), G(Sx_{n-1}, Sx_n, Sx_n), G(Sx_{n-1}, Sx_n, Sx_n), G(Sx_n, Sx_{n+1}, Sx_{n+1}), G(Sx_{n-1}, Sx_n, Sx_n) + G(Sx_n, Sx_{n+1}, Sx_{n+1}), 0) \leq 0.$$

By (F_a) we obtain

$$G(Sx_n, Sx_{n+1}, Sx_{n+1}) \leq \phi_1(G(Sx_{n-1}, Sx_n, Sx_n)) \leq \phi_1^2(G(Sx_{n-2}, Sx_{n-1}, Sx_{n-1})) \vdots \leq \phi_1^n(G(Sx_0, Sx_1, Sx_1)).$$

Then for $m > n$, and by G_5

$$G(Sx_n, Sx_m, Sx_m) \leq G(Sx_n, Sx_{n+1}, Sx_{n+1}) + \dots + G(Sx_{m-1}, Sx_m, Sx_m) \leq \phi_1^n(G(Sx_0, Sx_1, Sx_1)) + \dots + \phi_1^{m-1}(G(Sx_0, Sx_1, Sx_1)) = \sum_{k=n}^{m-1} \phi_1^k(G(Sx_0, Sx_1, Sx_1)).$$

Since $\sum_{k=n}^{\infty} \phi_1^k(G(Sx_0, Sx_1, Sx_1)) < \infty$, then for any $\varepsilon > 0$, there exists $k \in \mathbb{N}$ such that for $m > n \geq k, \sum_{k=n}^{m-1} \phi_1^k(G(Sx_0, Sx_1, Sx_1)) < \varepsilon$. Hence by Lemma (2.2) (Sx_n) is a G -Cauchy sequence. Since $S(X)$ is a G -complete metric subspace of X , there exists a point q in $S(X)$ such that $\lim_{n \rightarrow \infty} Sx_n = q$.

Also, we can find a point $p \in X$ such that $Sp = q$. We prove that $Tp = Sp$. By (2) we have

$$F(G(Tx_{n-1}, Tp, Tp), G(Sx_{n-1}, Sp, Sp), G(Sx_{n-1}, Tx_{n-1}, Tx_{n-1}), G(Sp, Tp, Tp), G(Sx_{n-1}, Tp, Tp), G(Sp, Tx_{n-1}, Tx_{n-1})) \leq 0, F(G(Sx_n, Tp, Tp), G(Sx_{n-1}, Sp, Sp),$$

$$\begin{aligned}
&G(Sx_{n-1}, Sx_n, Sx_n), G(Sp, Tp, Tp), \\
&G(Sx_{n-1}, Tp, Tp), G(Sp, Sx_n, Sx_n)) \leq 0. \\
&\text{Letting } n \text{ tend to infinity, we obtain} \\
&F(G(Sp, Tp, Tp), 0, 0, G(Sp, Tp, Tp), \\
&G(Sp, Tp, Tp), 0) \leq 0,
\end{aligned}$$

By (F_a) it follows that there exists a function $\phi_1 \in \phi$ such that $G(Sp, Tp, Tp) \leq \phi_1(0) = 0$, a contradiction. Hence $Tp = Sp$. Then $Tp = Sp = q$ is a point of coincidence of T and S . By Lemma (4.3), q is the unique point of coincidence. Moreover, if T and S are weakly compatible, by Lemma (4.2), q is the unique common fixed point of T and S .

Remark 4.3. If we put $S = I$, where I is the identity mapping, we have the Corollary (4.1).

Now, we extend the above theorem for four mappings in G -metric space.

Theorem 4.4. Let (X, G) be a symmetric G -metric space and $A, B, S, T: (X, G) \rightarrow (X, G)$ satisfying condition (3) for all $x, y \in X$, where $F \in \mathbf{F}_\phi$, such that

- (a) $T(X) \subseteq A(X)$ and $B(X) \subseteq S(X)$,
- (b) the pairs (A, B) and (T, S) are weakly compatible,
- (c) one of $A(X), B(X), S(X)$, or $T(X)$ is a G -complete subspace of X . Then A, B, S , and T have a unique common fixed point.

Proof. Let x_0 be an arbitrary point of X . From (a) we can choose $x_1, x_2 \in X$ such that $y_0 = Tx_0 = Ax_1$ and $y_1 = Bx_1 = Sx_2$. Continuing this process, we obtain

$$\begin{aligned}
&y_{2n} = Tx_{2n} = Ax_{2n+1}, y_{2n+1} = Bx_{2n+1} = \\
&Sx_{2n+2}, \text{ for } n = 0, 1, 2, \dots. \text{ Then, by (3) we have} \\
&\text{successively} \\
&F(G(Tx_{2n}, Bx_{2n+1}, Bx_{2n+1}), \\
&G(Sx_{2n}, Ax_{2n+1}, Ax_{2n+1}), G(Sx_{2n}, \\
&Tx_{2n}, Tx_{2n}), \\
&G(Ax_{2n+1}, Bx_{2n+1}, Bx_{2n+1}), G(Sx_{2n}, \\
&Bx_{2n+1}, Bx_{2n+1}), G(Ax_{2n+1}, \\
&Tx_{2n}, Tx_{2n})) \leq 0, \\
&F(G(y_{2n}, y_{2n+1}, y_{2n+1}), G(y_{2n-1}, y_{2n}, y_{2n}), \\
&G(y_{2n-1}, y_{2n}, y_{2n}), G(y_{2n}, y_{2n+1}, y_{2n+1}),
\end{aligned}$$

$$\begin{aligned}
&G(y_{2n-1}, y_{2n+1}, y_{2n+1}), 0) \leq 0. \\
&\text{By } (F_1) \text{ and } (G_5) \text{ we obtain} \\
&F(G(y_{2n}, y_{2n+1}, y_{2n+1}), G(y_{2n-1}, y_{2n}, y_{2n}), \\
&G(y_{2n-1}, y_{2n}, y_{2n}), G(y_{2n}, y_{2n+1}, y_{2n+1}), \\
&G(y_{2n-1}, y_{2n}, y_{2n}) + \\
&G(y_{2n}, y_{2n+1}, y_{2n+1}), 0) \leq 0.
\end{aligned}$$

$$\begin{aligned}
&\text{By } (F_a) \text{ we obtain} \\
&(y_{2n}, y_{2n+1}, y_{2n+1}) \leq \phi_1(G(y_{2n-1}, y_{2n}, y_{2n})) \\
&\leq \phi_1^2(G(y_{2n-2}, y_{2n-1}, y_{2n-1})) \\
&\leq \phi_1^n(G(y_0, y_1, y_1)).
\end{aligned}$$

Hence, for all n even or odd we have

$$G(y_n, y_{n+1}, y_{n+1}) \leq \phi_1^n(G(y_0, y_1, y_1)).$$

Then for $m > n$ and by G_5 we obtain

$$\begin{aligned}
&G(y_n, y_m, y_m) \\
&\leq G(y_n, y_{n+1}, y_{n+1}) + \dots + G(y_{m-1}, y_m, y_m) \\
&\leq \phi_1^n(G(y_0, y_1, y_1)) + \dots + \phi_1^{m-1}(G(y_0, y_1, y_1)) \\
&= \sum_{k=n}^{m-1} \phi_1^k(G(y_0, y_1, y_1)).
\end{aligned}$$

Since $\sum_{k=n}^{\infty} \phi_1^k(G(y_0, y_1, y_1)) < \infty$, then for any $\varepsilon > 0$, there exists $k \in \mathbb{N}$ such that for $m > n \geq k$, $\sum_{k=n}^{m-1} \phi_1^k(G(y_0, y_1, y_1)) < \varepsilon$. Hence by Lemma (2.2) (y_n) is a G -Cauchy sequence. Let $A(X)$ is G -complete subspace of X , there exists a point q in $A(X)$, such that

$$\lim_{n \rightarrow \infty} y_{2n} = \lim_{n \rightarrow \infty} Tx_{2n} = \lim_{n \rightarrow \infty} Ax_{2n+1} = q.$$

Also, we can find a point $p \in X$ such that $Ap = q$. Since $\lim_{n \rightarrow \infty} y_{2n} = q$, then also

$$\begin{aligned}
&\lim_{n \rightarrow \infty} y_{2n+1} = \lim_{n \rightarrow \infty} Bx_{2n+1} = \\
&\lim_{n \rightarrow \infty} Sx_{2n+2} = q. \text{ We prove that } Bp = Ap. \text{ By} \\
&(3) \text{ we have}
\end{aligned}$$

$$\begin{aligned}
&F(G(Tx_{2n}, Bp, Bp), G(Sx_{2n}, Ap, Ap), G(Sx_{2n}, \\
&Tx_{2n}, Tx_{2n}), G(Ap, Bp, Bp), \\
&G(Sx_{2n}, Bp, Bp), G(Ap, Tx_{2n}, Tx_{2n})) \leq 0,
\end{aligned}$$

Letting n tend to infinity, we obtain

$$F(G(q, Bp, Bp), 0, 0, G(q, Bp, Bp), G(q, Bp, Bp), 0) \leq 0.$$

By (F_a) it follows that there exists a function $\phi_1 \in \phi$ such that $G(q, Bp, Bp) \leq \phi_1(0) = 0$, a contradiction. Hence $Bp = q$. Then $Bp = Ap =$

q is a point of coincidence of A and B . Since (A, B) is weakly compatible then $Aq = ABp = BAp = Bq$. Since $B(X) \subseteq S(X)$, $Bp = q$ then $q \in S(X)$, so there is $r \in X$ such that $Sr = q$. We prove $Tr = q$. By (3) we obtain successively

$$\begin{aligned} &F(G(Tr, Bp, Bp), G(Sr, Ap, Ap), \\ &G(Sr, Tr, Tr), G(Ap, Bp, Bp), G(Sr, Bp, Bp), \\ &G(Ap, Tr, Tr)) \leq 0, \\ &F(G(Tr, q, q), 0, G(q, Tr, Tr), 0, 0, \\ &G(q, Tr, Tr)) \leq 0. \end{aligned}$$

Since (X, G) is symmetric and by (F_b) there exists a function $\phi_2 \in \phi$ such that $G(Tr, q, q) \leq \phi_2(0) = 0$. So $G(Tr, q, q) = 0$, hence $Tr = q$. Therefore $Tr = Sr = q$. Since (S, T) is weakly compatible then $Sq = STr = TSr = Tq$. By (3) replacing $x = q$ and $y = q$ we obtain

$$\begin{aligned} &F(G(Tq, Bq, Bq), G(Tq, Bq, Bq), 0, 0, \\ &G(Tq, Bq, Bq), G(Bq, Tq, Tq)) \leq 0. \end{aligned}$$

Since (X, G) is symmetric and by (F_3) , there exists a function $\phi_3 \in \phi$ such that

$$\begin{aligned} G(Tq, Bq, Bq) &\leq \phi_3(G(Bq, Tq, Tq)) \\ &= \phi_3(G(Tq, Bq, Bq)) \\ &< G(Tq, Bq, Bq), \end{aligned}$$

a contradiction. Hence $Tq = Bq$. Therefore $Tq = Sq = Aq = Bq$. By (3) we obtain

$$\begin{aligned} &F(G(Tq, Bp, Bp), G(Tq, Bp, Bp), 0, 0, \\ &G(Tq, Bp, Bp), G(Bp, Tq, Tq)) \leq 0, \\ &F(G(Tq, q, q), G(Tq, q, q), 0, 0, \\ &G(Tq, q, q), G(q, Tq, Tq)) \leq 0. \end{aligned}$$

Since (X, G) is symmetric and by (F_3) we conclude $Tq = q$. Therefore $Tq = Sq = Aq = Bq = q$, so q is a common fixed point of A, B, T , and S . By Lemma (4.4), q is the unique common fixed point of A, B, T , and S . In the cases for $B(X)$, $S(X)$ or $T(X)$ is a G -complete subspace of X the proof is similar.

Remark 4.5. If we put $B = T$ and $A = S$ we have Theorem (4.2).

By Example (3.5) and theorem (4.4) we get the following corollary.

Corollary 4.2. Let (X, G) be a symmetric G -metric space and $A, B, S, T : (X, G) \rightarrow (X, G)$ satisfying the condition

$$\begin{aligned} &G(Tx, By, By) \\ &\leq k \max\{G(Sx, Ay, Ay), G(Sx, Tx, Tx), \\ &G(Ay, By, By), G(Sx, By, By), G(Ay, Tx, Tx)\}, \end{aligned} \quad (7)$$

for all $x, y \in X$, where $k \in [0, \frac{1}{2})$, such that:

- (a) $T(X) \subseteq A(X)$ and $B(X) \subseteq S(X)$,
- (b) the pairs (A, B) and (T, S) are weakly compatible,
- (c) one of $A(X), B(X), S(X)$, or $T(X)$ is a G -complete subspace of X .

Then A, B, S , and T have a unique common fixed point.

Remark 4.6. Also, by Examples in [24] and Examples (3.3), (3.4) we have a new result.

Example 4.7. Let $X = [0, \infty)$ with the symmetric G -metric space $G(x, y, z) = |x - y| + |y - z| + |z - x|$,

and A, B, S and T are self mappings of X defined by

$$\begin{aligned} Tx &= \begin{cases} 0, & \text{if } x \in [0, 1) \\ 1, & \text{if } x \in [1, \infty) \end{cases}, & Sx &= \begin{cases} 3, & \text{if } x \in [0, 1) \\ \frac{1}{x}, & \text{if } x \in [1, \infty) \end{cases} \\ Ax &= \begin{cases} 0, & \text{if } x \in [0, 1) \\ \frac{1}{\sqrt{x}}, & \text{if } x \in [1, \infty) \end{cases}, & Bx &= 1, \text{ if } x \in [0, \infty), \end{aligned}$$

Clearly $T(X) \subseteq A(X)$ and $B(X) \subseteq S(X)$, $A(X)$ is G -complete subspace of X , and the pairs (T, S) and (A, B) are weakly compatible. Take the implicit relation defined as $F(t_1, \dots, t_6) = t_1 - k \max\{t_2, t_3, t_4, t_5, t_6\}$, where $k \in (0, \frac{1}{2})$. Then

$$\begin{aligned} t_1 &= 2|Tx - By|, & t_2 &= 2|Sx - Ay|, \\ t_3 &= 2|Sx - Ty|, & t_4 &= 2|Ax - By|, \\ t_5 &= 2|Sx - By|, & t_6 &= 2|Ay - Tx|. \end{aligned}$$

- If $x, y \in [0, 1)$ we obtain that $t_2 = t_3 = \max\{t_2, t_3, t_4, t_5, t_6\}$, and $t_1 \leq \frac{1}{3} \max\{t_2, t_3, t_4, t_5, t_6\}$.
- If $x, y \in [1, \infty)$ we obtain that $t_1 = 0$ so we are done and choose $k = \frac{1}{3}$.
- If $x \in [0, 1)$ and $y \in [1, \infty)$ we obtain that $t_3 = \max\{t_2, t_3, t_4, t_5, t_6\}$, and $t_1 \leq \frac{1}{3} \max\{t_2, t_3, t_4, t_5, t_6\}$.

- If $x \in [1, \infty)$ and $y \in [0, 1)$ we obtain that $t_1 = 0$ so we done and choose $k = \frac{1}{3}$,

the inequality (7) holds for all $x, y \in X$. The hypotheses of Corollary (4.2) satisfied, and 1 is the unique common fixed point of the mappings A, B, S and T .

5. CONCLUSIONS

In this paper, we introduced some common fixed point theorems for two and four mappings satisfying Φ^- implicit relation in G -metric spaces and a common fixed point theorem for T -contraction is proved. The results improved the results of Popa and Patriciu [24].

6. ACKNOWLEDGEMENTS

The authors are thankful to the referees and editors for careful reading of our research article

7. REFERENCES

1. Abbas, M. & B. E Rhoades. Common fixed point results for non-commuting mappings without continuity in generalized metric spaces. *Applied Mathematics and Computation* 215: 262–269 (2009).
2. Altun, I. & D. Turkoglu. Some fixed point theorems for weakly compatible mappings satisfying an implicit relation. *Taiwanese Journal of Mathematics* 13(4): 1291–1304 (2009).
3. Beiranvand, A., S. Moradi, M. Omid, & H. Pazandeh. Two fixed point theorem for special mapping. *arXiv:0903.1504v1 [math. FA]* (2009).
4. Chung, R., T. Kasian, A. Rasie & B.E. Rhoades. Property (P) in G -metric spaces. *Fixed Point Theory and Applications*. Art. ID 401684, p. 12 (2010).
5. Jungck, G. Commuting mappings and fixed points. *The American Mathematical Monthly* 73: 261–263 (1976).
6. Jungck, G. Compatible mappings and common fixed points. *International Journal of Mathematics and Mathematical Sciences* 9: 771–779 (1986).
7. Jungck, G. & B.E. Rhoades. Fixed Points for set valued functions without continuity. *Indian Journal of Pure and Applied Mathematics* 29: 227–238 (1998).
8. Karayian H. & M. Telci. Common fixed points of two maps in complete G -metric spaces. *Scientific Studies Research Service Mathematics Information, University of Alecsandri Bac̃au* 20(2): 39–48 (2010).
9. Manro, S., S.S. Bhatia & S. Kumar. Expansion mappings theorems in G -metric spaces. *International Journal of Contemporary Mathematical Sciences*, 5(51): 2529–2535 (2010).
10. Moradi, S. Kannan fixed point theorem on complete metric spaces and on generalized metric spaces depend on another function. *ArXiv:0903.1577v1 [math. FA]* (2009).
11. Morales, J. R. & E. Rojas. Cone metric spaces and fixed point theorems of T -Kannan contractive mappings. *International Journal of Mathematical Analysis* 4(4): 175–184 (2010).
12. Morales, J. R. & E. Rojas. T -Zamfirescu and T -weak contraction mappings on cone metric spaces. *arxiv:0909.1255v1. [math. FA]*.
13. Mustafa, Z. & H. Obiedat. A fixed point theorem of Reich in G -metric spaces. *Cubo A Mathematical Journal* 12: 83–93 (2010).
14. Mustafa, Z., H. Obiedat & F. Awawdeh. Some fixed point theorems for mappings on G -complete metric spaces. *Fixed Point Theory and Applications*, Article ID 189870, p.12 (2008).
15. Mustafa, Z., W. Shatanawi & M. Bataineh fixed point theorem on un-complete G -metric spaces. *Journal of Mathematics and Statistics* 4(4): 190–201 (2008).
16. Mustafa, Z., W. Shatanawi & M. Bataineh. Existence of fixed point results in G -metric Spaces. *International Journal of Mathematics and Mathematical Sciences* Article ID 283028, 10 pp. (2009).
17. Mustafa, Z. & B. Sims. Some remarks concerning D -metric spaces. *Intern. Conf. Fixed Point. Theory and Applications, Yokohama* 189–198 (2004).
18. Mustafa, Z. & B. Sims. A new approach to generalized metric spaces. *Journal of Nonlinear Convex Analysis* 7: 289–297 (2006).
19. Mustafa, Z. & B. Sims. Fixed point theorems for contractive mappings in complete G -metric spaces. *Fixed Point Theory and Applications*, Article ID 917175, 10 pp. (2009).
20. Obiedat, H. & Z. Mustafa. Fixed point results on non-symmetric G -metric spaces. *Jordan Journal of Mathematics and Statistics* 3(2): 39–48 (2010).
21. Pathak, H.K. Fixed point theorems for weak compatible multi-valued and single valued mappings. *Acta Mathematica Hungaria* 67 (1-2): 69–78 (1995).
22. Popa, V. Fixed point theorems for implicit contractive mappings. *Stud. Cerc. St. Ser. Mat., Univ. Bac̃au*, 7: 129–133 (1997).
23. Popa, V. Some fixed point theorems for compatible mappings satisfying implicit relations. *Demonstration Math.* 32: 157–163 (1999).
24. Popa, V. & A. Patriciu. A general fixed point theorem for mappings satisfying an Φ -implicit relation in complete G -metric space. *Gazi University Journal of Science* 25(2): 403–408 (2012).
25. Sessa, S. On a weak commutativity condition of mappings in fixed point considerations. *Publ. Inst. Math. (Beograd)(N.S.)* 32: 149–153 (1982).
26. Shatanawi, W. Fixed point theory for contractive mappings satisfying Φ -maps in G -metric spaces. *Fixed Point Theory and Applications*, Article ID 181650, 9 pp. (2010).
27. Sumitra, R., V. Rhymend Uthariaraj & R. Hemavathy. Common fixed point theorem for T -Hardy-Rogers contraction mapping in a cone metric space. *International Mathematical Forum* 5(30): 1495–1506 (2010).